

## 20.2 WT3P1

### Pitch Control Model for Type 3 Wind Generator (for WT3G1 and WT3G2)

This model is located at system bus #\_\_\_\_\_ IBUS,  
Machine identifier #\_\_\_\_\_ ID,  
This model uses CONs starting with #\_\_\_\_\_ J,  
and STATEs starting with #\_\_\_\_\_ K.

In blkmdl, this model requires one reserved ICON.

CONs	#	Value	Description
J			$T_p$ , Blade response time constant
J+1			$K_{pp}$ , Proportional gain of PI regulator (pu)
J+2			$K_{ip}$ , Integrator gain of PI regulator (pu)
J+3			$K_{pc}$ , Proportional gain of the compensator (pu)
J+4			$K_{ic}$ , Integrator gain of the compensator (pu)
J+5			TetaMin, Lower pitch angle limit (degrees)
J+6			TetaMax, Upper pitch angle limit (degrees)
J+7			RTetaMax, Upper pitch angle rate limit (degrees/sec)
J+8			$P_{MX}$ , Power reference, pu on MBASE

**Note:** When a WT operates with a partial output, the DSTATE(K+2) may show INITIAL CONDITION SUSPECT. In this case no actions are needed.

STATEs	#	Description
K		Output lag
K+1		Pitch control
K+2		Pitch compensation

IBUS, 'WT3P1', ID, CON(J) to CON (J+8) /

